

Eidgenössische Technische Hochschule Zürich Swiss Federal Institute of Technology Zurich



Beyond Nyquist – Accelerating Magnetic Resonance Imaging

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lt's useful...





R. Manka, G. Crelier

Magnetic Resonance Imaging



Encoding





Encoding

Data	Encoding	Object
d _ĸ	$= \int e^{j\vec{k}_{\kappa}\cdot\vec{x}}$	$\rho(\vec{x})d\vec{x}$
d _ĸ	$=\sum_{\xi} e^{j\vec{k}_{\kappa}\cdot\vec{x}_{\xi}}$	$\rho(\vec{\mathbf{x}}_{\xi})$
d	= E	ρ

Decoding



Linear decoding



Transform coding



Madore B et al. MRM 1999 Tsao J et al. MRM 2002





Harry Nyquist 1889-1976

Transform coding



n=1

Linear decoding





Tsao J et al. MRM 2003 Kozerke S et al. MRM 2004 Pedersen H et al. MRM 2009

k-t PCA



Pedersen H et al. MRM 2009 Vitanis V et al. IEEE 2010 Giese D et al. MRM 2013 Knobloch V et al. MRM 2013

Nonlinear decoding



Lustig M et al. MRM 2007 Gamper U et al. MRM 2008 Otazo R et al. ISMRM 2013

Compressed Sensing



Undersampling progress – Cardiac



Kellman P et al. MRM 2004Plein S et al. MRM 2007Plein S et al. Radiology 2005Jung B et al. JMRI 2008

Nayak KS et al. JCMR 2008 Vitanis V et al. MRM 2010 Otazo R et al. MRM 2010 Lingala SG et al. IEEE 2011



Reconstruction accuracy



R=1





R=16



J. Busch et al. MRM 2013

Divergence-free image reconstruction



Divergence-free image reconstruction





J. Busch et al. MRM 2013

Image reconstruction in non-linear feature spaces



Image space

Non-linear feature space

$$\vec{i} \rightarrow \vec{i}_{n+1} = \mathcal{P}_{kPCA}(\vec{i}_n - E^H(\vec{Ei}_n - \vec{d}))$$

Schmidt J et al. PLOS ONE 2016

Image reconstruction in non-linear feature spaces



Schmidt J et al. PLOS ONE 2016



Time

3D dynamic perfusion imaging





5x 2D k-t SENSE (1.1 x 1.1 mm²)

Plein S et al. MRM 2008, Radiology 2009

k-t PCA

10x k-t PCA (2.2x2.2x10 mm³)

Vitanis V et al. MRM 2011, Manka R et al. JACC 2011, Jogyia R et al. JACC 2012

3D Perfusion trial

3D Perfusion Multi-centre study

Manka R et al. Circ CVI 2015

10x 3D k-t PCA (2.2 x 2.2 mm²)

Schmidt JF et al. MRM 2013

Generic matrix description of motion

Batchelor P et al. MRM 2005 Schmidt JF et al. MRM 2011

Data-driven motion correction

k-t PCA^{mc}

Schmidt JF et al. MRM 2013

Data-driven motion correction

10x 3D k-t PCA

10x 3D k-t PCAmc

Schmidt JF et al. MRM 2013

3D MR Perfusion + CT Angiography

Manka R et al. Eur Heart J 2011

Time

Chemical shift

Cell respiration

¹H, ¹⁹F, ³¹P, ¹³C

0.1-1 mM

Dissolution Dynamic Nuclear Polarization

Ardenkjaer-Larsen JH et al. PNAS 2003

Prototype polarizer

Batel M et al. JMR 2012

Dissolution dynamic nuclear polarization

Wespi P, Steinhauser J et al.

Weiss K et al. JAMR 2012

O h-Ici D et al. Radiology 2015

From bench to bedside

Nelson SJ et al. Science Transl Med 2013

Blood flow quantification – relative pressure maps

Flow field

Boundaries

Pressure field

Crelier G et al. GyroTools

Blood flow quantification

Pre operation

Post operation

Manka R, Busch J et al. Eur Heart J 2013

Blood flow quantification

Diffusion

Velocity compensated diffusion-weighted spin-echo

Gamper U et al. MRM 2007

Conformal mapping

Dynamic Diffusion Tensor Imaging

Stoeck C et al. PLOS ONE 2014

Laminar and turbulent flows

Universal signal model

Dyverfeldt P et al. MRM 2006

Bayesian parameter estimation

$$P(\Theta, \mathbf{B} \mid M, I) = \frac{P(\Theta, \mathbf{B} \mid I) P(M \mid \Theta, \mathbf{B}, I)}{(M \mid I)} \quad \Theta = [\sigma, v]$$
Incorporate bounds of parameters
$$P(M \mid I)$$
Incorporate knowledge about the noise
$$\int d\sigma_n d\mathbf{B}$$

$$P(\Theta \mid M, I)$$

Binter C et al. MRM 2012

Bayesian multi-point velocity encoding

Aortic valves in-vitro

St. Judes Medical®

Edwards® Sapien

TKE [J/m³]

Binter C et al. SCMR 2012

Aortic valves in-vivo

Energy Loss index

Binter C et al. SCMR 2012

Image-guided modeling and prediction

Genet M et al. J Applied Physiol 2014, J Biomech 2015

Big Data Processing

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